

On the next-to-last CG and MR iteration step

Petr Tichý^{†*}

joint work with

Jörg Liesen^{*}

[†]Institute of Computer Science AS CR,

^{*}Technical University of Berlin

March 13-18, 2005. ALGORITMY 2005 - Conference on Scientific Computing,
Vysoké Tatry, Podbanské, Slovakia



A system of linear algebraic equations

Consider a system of linear algebraic equations

$$\mathbf{A}x = b$$

$\mathbf{A} \in \mathbb{R}^{n \times n}$ is nonsingular and normal, $b \in \mathbb{R}^n$.

- How to construct an **approximation** to the solution?



A system of linear algebraic equations

Consider a system of linear algebraic equations

$$\mathbf{A}x = b$$

$\mathbf{A} \in \mathbb{R}^{n \times n}$ is nonsingular and normal, $b \in \mathbb{R}^n$.

- How to construct an approximation to the solution?

Krylov subspace methods \mapsto Given $x_0 \in \mathbb{R}^n$, $r_0 = b - \mathbf{A}x_0$. Find x_i ,

$$x_i \in x_0 + \mathcal{K}_i(\mathbf{A}, r_0) \quad \text{such that} \quad r_i \perp \mathcal{C}_i,$$

where $r_i = b - \mathbf{A}x_i$, $\mathcal{K}_i(\mathbf{A}, r_0) \equiv \text{span} \{r_0, \dots, \mathbf{A}^{i-1}r_0\}$.



OR and MR Krylov subspace methods

Let $x_0 = 0$, i.e. $r_0 = b - \mathbf{A}x_0 = b$ (for simplicity).

Orthogonal Residual (OR) and Minimal Residual (MR) approach

(OR) Find $x_i \in \mathcal{K}_i(\mathbf{A}, b)$ such that $r_i \perp \mathcal{K}_i(\mathbf{A}, b)$.

(MR) Find $x_i \in \mathcal{K}_i(\mathbf{A}, b)$ such that $r_i \perp \mathbf{A}\mathcal{K}_i(\mathbf{A}, b)$.



OR and MR Krylov subspace methods

Let $x_0 = 0$, i.e. $r_0 = b - \mathbf{A}x_0 = b$ (for simplicity).

Orthogonal Residual (OR) and Minimal Residual (MR) approach

(OR) Find $x_i \in \mathcal{K}_i(\mathbf{A}, b)$ such that $r_i \perp \mathcal{K}_i(\mathbf{A}, b)$.

(MR) Find $x_i \in \mathcal{K}_i(\mathbf{A}, b)$ such that $r_i \perp \mathbf{A}\mathcal{K}_i(\mathbf{A}, b)$.

Optimality properties

$$(OR) \quad \|e_i\|_{\mathbf{A}} = \min_{p \in \pi_i} \|p(\mathbf{A})x\|_{\mathbf{A}} \quad (\text{if } \mathbf{A} \text{ is SPD}),$$

$$(MR) \quad \|r_i\| = \min_{p \in \pi_i} \|p(\mathbf{A})b\|,$$

where $e_i \equiv x - x_i$, $\pi_i \equiv \{ p \text{ is a polynomial; } \deg(p) \leq i; p(0) = 1 \}$.



The problem of convergence

MR constructs approximations $x_i \in \mathcal{K}_i(\mathbf{A}, b)$ to the solution x of the system $\mathbf{A}x = b$ such that

$$\|r_i\| = \min_{p \in \pi_i} \|p(\mathbf{A}) b\|.$$

- **Our aim:**

Description and understanding of this minimization process.

- **Considered classes of matrices in this talk:**

Normal matrices, symmetric and positive definite matrices, symmetric positive definite tridiagonal Toeplitz matrices.

- We denote the OR method for SPD matrices as the CG method (Conjugate Gradient).



Outline

1. Introduction
2. Convergence bounds
3. Formulas for the next-to-last CG and MR iteration step
4. Application to symmetric tridiagonal Toeplitz matrices
5. Example: 1D Poisson equation
6. Conclusions



Convergence of the MR method

Let \mathbf{A} be **normal**, $L \equiv \{\lambda_1, \dots, \lambda_n\}$, $\|b\| = 1$. Then

$$\|r_i\| = \min_{p \in \pi_i} \|p(\mathbf{A})b\|$$



Convergence of the MR method

Let \mathbf{A} be normal, $L \equiv \{\lambda_1, \dots, \lambda_n\}$, $\|b\| = 1$. Then

$$\begin{aligned}\|r_i\| &= \min_{p \in \pi_i} \|p(\mathbf{A})b\| \\ &\leq \max_{\|b\|=1} \min_{p \in \pi_i} \|p(\mathbf{A})b\| \quad (\text{worst-case}) \\ &= \min_{p \in \pi_i} \|p(\mathbf{A})\| \\ &= \min_{p \in \pi_i} \max_{\lambda_j \in L} |p(\lambda_j)|\end{aligned}$$



Convergence of the MR method

Let \mathbf{A} be normal, $L \equiv \{\lambda_1, \dots, \lambda_n\}$, $\|b\| = 1$. Then

$$\begin{aligned}\|r_i\| &= \min_{p \in \pi_i} \|p(\mathbf{A})b\| \\ &\leq \max_{\|b\|=1} \min_{p \in \pi_i} \|p(\mathbf{A})b\| \quad (\text{worst-case}) \\ &= \min_{p \in \pi_i} \|p(\mathbf{A})\| \\ &= \min_{p \in \pi_i} \max_{\lambda_j \in L} |p(\lambda_j)|\end{aligned}$$

- In this sense we understand the MR-CG worst-case behaviour.
- How to describe $\|r_i\|$ or the worst-case bound in terms of input data?



General formula for the MR residual

Krylov matrix

$$\mathbf{K}_{i+1} \equiv [b, \mathbf{A}b, \dots, \mathbf{A}^i b].$$

Residual r_i can be written as (Assumption: \mathbf{K}_{i+1} has full column rank)

$$r_i = \|r_i\|^2 (\mathbf{K}_{i+1}^+)^H e_1 \Rightarrow \|r_i\| = \frac{1}{\|(\mathbf{K}_{i+1}^+)^H e_1\|}.$$

[Liesen & Rozložník & Strakoš '02, Ipsen '00]



General formula for the MR residual

Krylov matrix

$$\mathbf{K}_{i+1} \equiv [b, \mathbf{A}b, \dots, \mathbf{A}^i b].$$

Residual r_i can be written as (Assumption: \mathbf{K}_{i+1} has full column rank)

$$r_i = \|r_i\|^2 (\mathbf{K}_{i+1}^+)^H e_1 \Rightarrow \|r_i\| = \frac{1}{\|(\mathbf{K}_{i+1}^+)^H e_1\|}.$$

[Liesen & Rozložník & Strakoš '02, Ipsen '00]

We consider \mathbf{A} and b in the form

$$\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^H, \quad b = \mathbf{Q} [\rho_1, \dots, \rho_n]^T.$$

We will assume that all eigenvalues of \mathbf{A} are **distinct**.



The next-to-last MR iteration step

Let $q_j \neq 0$ for all j . Then

$$\|r_{n-1}\| = \left(\sum_{j=1}^n \left| \frac{l_j}{q_j} \right|^2 \right)^{-1/2}, \quad l_j \equiv \prod_{\substack{k=1 \\ k \neq j}}^n \frac{\lambda_k}{\lambda_k - \lambda_j}.$$

[Liesen & T. '04, Ipsen '00]



The next-to-last MR iteration step

Let $q_j \neq 0$ for all j . Then

$$\|r_{n-1}\| = \left(\sum_{j=1}^n \left| \frac{l_j}{q_j} \right|^2 \right)^{-1/2}, \quad l_j \equiv \prod_{\substack{k=1 \\ k \neq j}}^n \frac{\lambda_k}{\lambda_k - \lambda_j}.$$

[Liesen & T. '04, Ipsen '00]

Using Cauchy's inequality,

$$\frac{\|r_{n-1}^w\|}{\|b_{MR}^w\|} = \left(\sum_{j=1}^n |l_j| \right)^{-1},$$

where

$$b_{MR}^w = \mathbf{Q} [q_1^w, \dots, q_n^w]^T, \quad |q_k^w|^2 = \gamma |l_k|, \quad k = 1, \dots, n,$$

$\gamma > 0$ is any scaling factor.

[Liesen & T. '04]



The next-to-last CG iteration step

CG can be seen as MR for a special right hand side \tilde{b} ,

$$\min_{p \in \pi_i} \|p(\mathbf{A})x\|_{\mathbf{A}} = \min_{p \in \pi_i} \|p(\mathbf{A})\mathbf{A}^{1/2}x\| = \min_{p \in \pi_i} \|p(\mathbf{A})\tilde{b}\|.$$



The next-to-last CG iteration step

CG can be seen as MR for a special right hand side \tilde{b} ,

$$\min_{p \in \pi_i} \|p(\mathbf{A})x\|_{\mathbf{A}} = \min_{p \in \pi_i} \|p(\mathbf{A})\mathbf{A}^{1/2}x\| = \min_{p \in \pi_i} \|p(\mathbf{A})\tilde{b}\|.$$

Then

$$\|e_{n-1}\|_{\mathbf{A}} = \left(\sum_{j=1}^n \left| \frac{\lambda_j^{1/2} l_j}{\varrho_j} \right|^2 \right)^{-1/2}, \quad \frac{\|e_{n-1}^w\|_{\mathbf{A}}}{\|x_{CG}^w\|_{\mathbf{A}}} = \left(\sum_{j=1}^n |l_j| \right)^{-1},$$

$$b_{CG}^w = \mathbf{Q} [\varrho_1^w, \dots, \varrho_n^w]^T, \quad |\varrho_k^w|^2 = \gamma |\lambda_k l_k|, \quad k = 1, \dots, n,$$

$\gamma > 0$ is any scaling factor.

[Liesen & T. '05]



The information about the next-to-last step

The next-to-last step of CG and MR is completely understood!

We know

- the convergence quantities,
- the worst-case convergence quantities and corresponding b^w .



The information about the next-to-last step

The next-to-last step of CG and MR is completely understood!

We know

- the convergence quantities,
- the worst-case convergence quantities and corresponding b^w .

How to use this information?

- We can study the influence of the right hand side,
- we can compare true convergence quantities with convergence bounds,
- we can determine right hand sides leading to the slowest convergence and identify the worst input data of our original problem.



Symmetric tridiagonal Toeplitz matrices

Consider linear algebraic systems $\mathbf{A}x = b$, where

$$\mathbf{A} = \begin{bmatrix} \alpha & \beta & & & \\ \beta & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & & \beta & \alpha \end{bmatrix} \in \mathbb{R}^{n \times n}.$$

Let α and β be such that \mathbf{A} is **symmetric and positive definite** matrix.



Symmetric tridiagonal Toeplitz matrices

Consider linear algebraic systems $\mathbf{A}x = b$, where

$$\mathbf{A} = \begin{bmatrix} \alpha & \beta & & & \\ \beta & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \beta & \alpha \end{bmatrix} \in \mathbb{R}^{n \times n}.$$

Let α and β be such that \mathbf{A} is **symmetric and positive definite** matrix.

Eigenvalues and eigenvectors of \mathbf{A} are known

$$\lambda_k = \alpha + 2\beta \cos(k\pi h),$$

$$q_k = (2h)^{1/2} [\sin(k\pi h), \sin(2k\pi h), \dots, \sin(nk\pi h)]^T,$$

where $h \equiv (n + 1)^{-1}$.



Worst-case bound versus classical κ -bound

Now we are able to determine l_j and the worst-case bound

$$\frac{\|e_{n-1}^w\|_A}{\|e_0^w\|_A} = \left(\sum_{j=1}^n |l_j| \right)^{-1} \approx \frac{2\nu^{n-1}}{1 + \nu^2 + \dots + \nu^{2(n-1)} + \nu^{2n}},$$

where

$$\nu \equiv \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1}, \quad \kappa = \frac{\lambda_{max}}{\lambda_{min}}.$$



Worst-case bound versus classical κ -bound

Now we are able to determine l_j and the worst-case bound

$$\frac{\|e_{n-1}^w\|_A}{\|e_0^w\|_A} = \left(\sum_{j=1}^n |l_j| \right)^{-1} \approx \frac{2\nu^{n-1}}{1 + \nu^2 + \dots + \nu^{2(n-1)} + \nu^{2n}},$$

where

$$\nu \equiv \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1}, \quad \kappa = \frac{\lambda_{max}}{\lambda_{min}}.$$

The classical κ -bound is given by

$$\frac{\|e_{n-1}^w\|_A}{\|e_0^w\|_A} \leq 2\nu^{n-1}.$$



Model problem: Poisson equation

$$-u''(z) = f(z), \quad z \in (0, 1), \quad u(0) = u_0, \quad u(1) = u_1.$$

The central finite difference approximation on the uniform grid kh , $k = 1, \dots, n$, $h = 1/(n+1)$, leads to a system $\mathbf{A}x = b$

$$\overbrace{\begin{bmatrix} 2 & -1 & & & \\ -1 & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & -1 \\ & & & -1 & 2 \end{bmatrix}}^{\mathbf{A}} x = h^2 \overbrace{\begin{bmatrix} f(h) \\ \vdots \\ \vdots \\ f(nh) \end{bmatrix}}^b + \begin{bmatrix} u_0 \\ \\ \\ u_1 \end{bmatrix}.$$

The eigenvalues λ_k and the eigenvectors q_k of \mathbf{A} are known,

$$\lambda_k = 4 \sin^2 \left(\frac{k\pi h}{2} \right) \Rightarrow l_j = 2 \cos^2 \left(\frac{j\pi h}{2} \right).$$

[Liesen & T. '05]



Various right hand sides

Formulas for the next-to-last step

$$\|r_{n-1}\| = \left(\sum_{j=1}^n \left| \frac{l_j}{\varrho_j} \right|^2 \right)^{-1/2}, \quad \|e_{n-1}\|_{\mathbf{A}} = \left(\sum_{j=1}^n \left| \frac{\lambda_j^{1/2} l_j}{\varrho_j} \right|^2 \right)^{-1/2}.$$

We consider two types of right hand sides:

- **worst-case b 's**: right hand sides leading to maximal relative convergence quantities in the next-to-last step $\rightarrow b_{MR}^w, b_{CG}^w$.
- **unbiased b** $\rightarrow b^u$, all ϱ_j are of equal size.



Some results for MR

Let $\|b_{MR}^w\| = \|b^u\| = 1$.

[Liesen & T. '05]

Worst-case \times **unbiased case (MR)**

$$\|r_{n-1}^w\| = \frac{1}{n}, \quad \|r_{n-1}^u\| > \sqrt{\frac{2}{3}} \frac{1}{n}.$$



Some results for MR

Let $\|b_{MR}^w\| = \|b^u\| = 1$.

[Liesen & T. '05]

Worst-case \times **unbiased case (MR)**

$$\|r_{n-1}^w\| = \frac{1}{n}, \quad \|r_{n-1}^u\| > \sqrt{\frac{2}{3}} \frac{1}{n}.$$

Exact convergence curve

[idee by Naiman & Babuška & Elman '97]

$$\|r_i\| = \left[\frac{n-i}{n(i+1)} \right]^{1/2} \quad \text{MR}(\mathbf{A}, b_{MR}^w).$$



Some results for MR

Let $\|b_{MR}^w\| = \|b^u\| = 1$.

[Liesen & T. '05]

Worst-case \times **unbiased case (MR)**

$$\|r_{n-1}^w\| = \frac{1}{n}, \quad \|r_{n-1}^u\| > \sqrt{\frac{2}{3}} \frac{1}{n}.$$

Exact convergence curve

[idee by Naiman & Babuška & Elman '97]

$$\|r_i\| = \left[\frac{n-i}{n(i+1)} \right]^{1/2} \quad \text{MR}(\mathbf{A}, b_{MR}^w).$$

Worst data for MR

$$u(0) = 0, \quad u(1) = 0, \quad f(z) \approx \cot\left(\frac{\pi z}{2}\right)$$

yield a worst right-hand side for MR.



Worst data for CG

We are able to determine **worst** ϱ^w , corresponding $b^w = \mathbf{Q}\varrho^w$.

$$\begin{array}{ccc} \text{worst } \varrho & & b_{CG}^w & & \text{data for diff. eq.} \\ \left[\begin{array}{c} \sin(\pi h) \\ \vdots \\ \sin(n\pi h) \end{array} \right] & \leftrightarrow & \left[\begin{array}{c} 1 \\ 0 \\ \vdots \\ 0 \end{array} \right] & \leftrightarrow & \begin{array}{l} f(z) = 0, \\ u(0) = 1, \\ u(1) = 0. \end{array} \end{array}$$

CG started with $x_0 = 0$ and b_{CG}^w attains the worst-case relative A -norm of the error in the $(n - 1)$ st iteration step.



Worst data for CG

We are able to determine **worst** ϱ^w , corresponding $b^w = \mathbf{Q}\varrho^w$.

$$\begin{array}{ccc} \text{worst } \varrho & & b_{CG}^w & & \text{data for diff. eq.} \\ \left[\begin{array}{c} \sin(\pi h) \\ \vdots \\ \sin(n\pi h) \end{array} \right] & \leftrightarrow & \left[\begin{array}{c} 1 \\ 0 \\ \vdots \\ 0 \end{array} \right] & \leftrightarrow & \begin{array}{l} f(z) = 0, \\ u(0) = 1, \\ u(1) = 0. \end{array} \end{array}$$

CG started with $x_0 = 0$ and b_{CG}^w attains the worst-case relative A -norm of the error in the $(n - 1)$ st iteration step.

Another example: Let n be even.

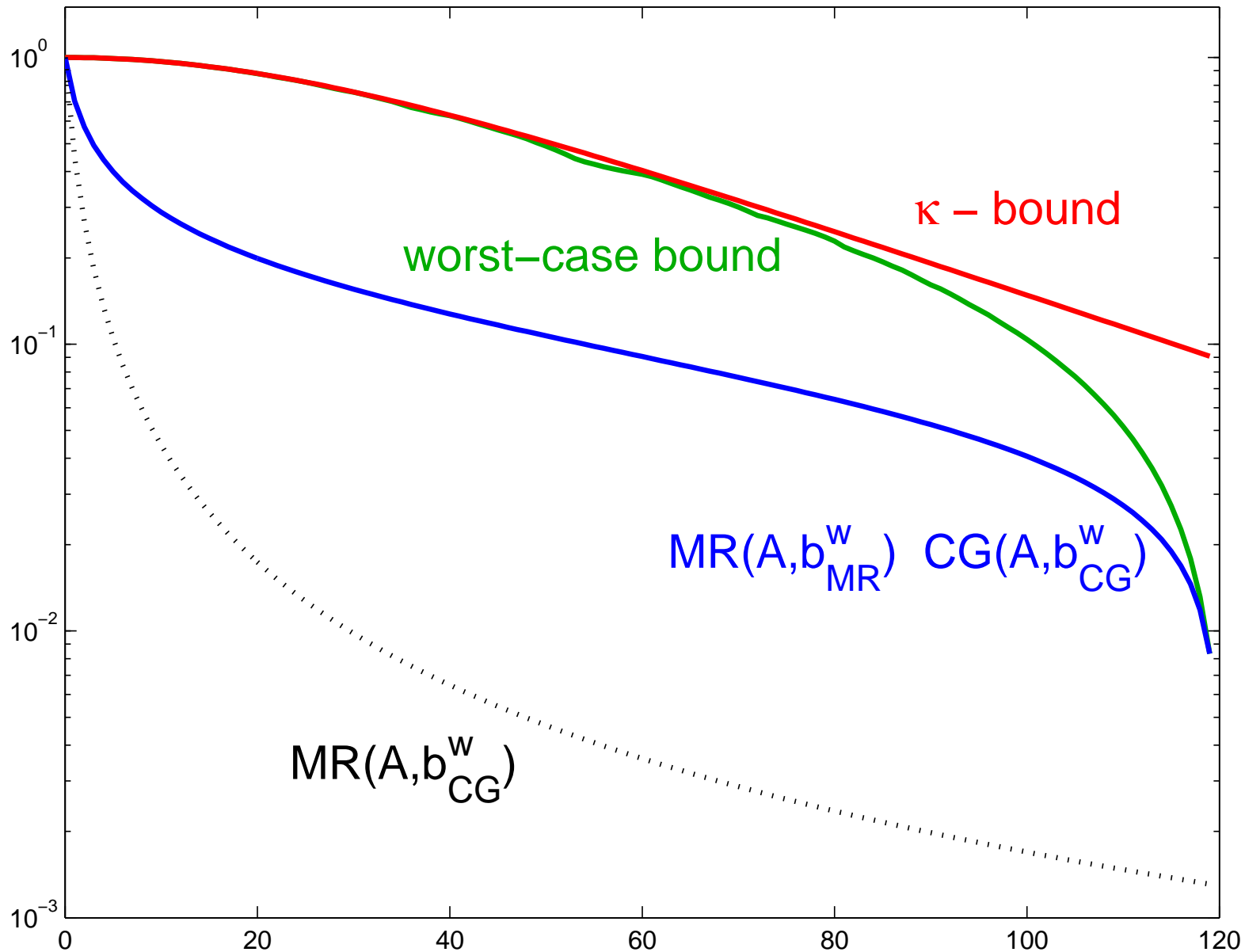
$$u''(z) = 0, \quad u(0) = 1, \quad u(1) = 1 \quad \implies \quad b = [1, 0, \dots, 0, 1]^T.$$

Then $\|x - x_{n/2}\|_A / \|x\|_A$ is the worst possible one and CG finds the solution in the following step.

[Liesen & T. '05]



Numerical experiment





Conclusions

- Our results for normal matrices: [Liesen & T. '04]
 - allow to study model problems with known eigenvalues,
 - can be formulated for CG and MR.



Conclusions

- Our results for normal matrices: [Liesen & T. '04]
 - allow to study model problems with known eigenvalues,
 - can be formulated for CG and MR.
- [Liesen & T. '05]
- **The next-to-last step of CG and MR is completely understood!**
- We can compare true convergence quantities with convergence bounds.
- For 1-D Poisson equation we obtained interesting results:
 - particular worst-case quantities in the next-to-last step,
 - implications for the connection between the differential equation and the linear solver for the discretized problem,
 - exact convergence curves for particular right-hand sides.



Thank you for your attention!



Thank you for your attention!

More details can be found in

Liesen, J. and Tichý, P., The worst-case GMRES for normal matrices, BIT Numerical Mathematics, Volume 44, pp. 79-98, 2004.

Liesen, J. and Tichý, P., On the next-to-last CG and MR iteration step, submitted to ETNA, January 2005.

See also <http://www.math.tu-berlin.de/~tichy>