Solving sequences of linear systems by preconditioned iterative methods

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joint work with

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- 1. Motivation
- 2. Our goal: Reuse of matrix approximations / preconditioners
- 3. Reuse of structural information (preconditioner patterns)
- 4. Reuse of structural + numerical information (preconditioners)
- 5. Conclusions



1. Solving systems of nonlinear equations

$$F(x) = 0$$

Sequences of linear systems of the form

 \Downarrow

$$J(x_k)\Delta x = -F(x_k), \ J(x_k) \approx F'(x_k)$$

solved until for some $k, k = 1, 2, \ldots$

 $\|F(x_k)\| < tol$

 $J(x_k)$ may change at points influenced by nonlinearities



2. Solving nonlinear convection-diffusion problems

$$-\Delta u + u\nabla u = f$$

E.g., from the upwind discretization in 2D, with $u \ge 0$ we get for grid internal nodes (i, j)

 \Downarrow

$$u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} - 4u_{ij} + hu_{ij}(2u_{ij} - u_{i-1,j} - u_{i,j-1}) = h^2 f_{ij}$$

It is a matrix with five diagonals

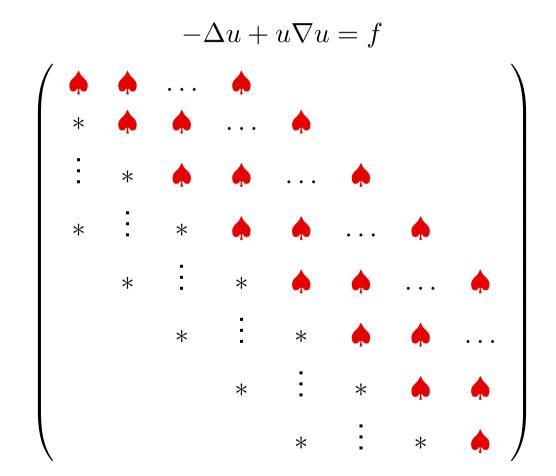
Entries in its three diagonals may change in subsequent linear systems

2. Solving nonlinear convection-diffusion problems (continued)

 $-\Delta u + u\nabla u = f$



2. Solving nonlinear convection-diffusion problems (continued)





3. Solving equations with a parabolic term

$$\frac{\partial u}{\partial t} - \Delta u = f$$

E.g., 2D problem with 2^{nd} order centered differences in space and backward Euler time discretization for grid internal nodes (i, j) and time step t + 1

 \Downarrow

$$h^{2}(u_{ij}^{t+1} - u_{ij}^{t}) + \tau(u_{i+1,j}^{t+1} + u_{i-1,j}^{t+1} + u_{i,j+1}^{t+1} + u_{i,j-1}^{t+1} - 4u_{ij}^{t+1}) = h^{2}\tau f_{ij}^{t+1}$$

Again, we get a matrix with five diagonals

Diagonal entries may change with time steps



Reuse of approximations of matrices in sequences of linear systems

Solving sequences of systems of linear equations

$$A^0 x = b^0, \ A^1 x = b^1, \ \dots$$

by preconditioned iterative methods with preconditioners M^0, M^1, \ldots

Goal: computing M^{i+k} from A^{i+k} for some $k \ge 1$, and possibly reuse additional information from M^i and A^i .



2. Our goal / Reuse of approximations: II.

Two basic strategies for the information reuse



2. Our goal / Reuse of approximations: II.

Two basic strategies for the information reuse

- 1. Reuse of matrix patterns
 - Using pattern of M^i .
 - Using pattern of \widehat{A}_i (A_i , or a part of A_i).



2. Our goal / Reuse of approximations: II.

Two basic strategies for the information reuse

- 1. Reuse of matrix patterns
 - Using pattern of M^i .
 - Using pattern of \widehat{A}_i (A_i , or a part of A_i).
- 2. Reuse of both patterns and values
 - Using entries of M^i .
 - Using entries of \widehat{A}_i (A_i , or a part of A_i).



Some related work

- Preconditioners from quasi-Newton updates (Morales, Nocedal, 2000)
- Freezing approximate Jacobians over a couple of subsequent systems (MNK: Shamanskii, 1967; Brent, 1973).
- Freezing the preconditioner over a couple of subsequent systems (MFNK: Knoll, McHugh, 1998).
- Some simple preconditioners (e.g., Jacobi, ILU(0) for PDEs) may be readily available even in parallel and/or matrix-free environment
- Preconditioners from a related matrix, operator (e.g., based on orthogonal grid, Truchas code, LANL, 2003; cf. Knoll, Keyes, 2004) a lot of approaches)
- Solving systems in adaptive filtering by incomplete factorizations + iterative refinement (Comon, Trystram, 1987)
- Approximate diagonal updates (Benzi, Bertaccini, 2003; Bertaccini, 2004)



Some related work (continued)

- World of updates of Krylov subspaces (e.g., Morgan 1995-2002); Baglama, Calvetti, Golub, Reichel, 1999; Carpentieri et. al., 2003; de Sturler, 1996; Erhel, Burrage, Pohl, 1996; Duff, Giraud, Langou, Martin, 2005; Giraud et. al. 2004–2005; Parks et al. 2004)
- Dense updates of decompositions (Bartels, Golub, Saunders, 1970; Gill, Golub, Murray, Saunders, 1974)
- Sparse updates of decompositions (Hager, Davis, 1999–2004).



Some related work (continued)

 Use of cheap matrix estimations based on graph coloring techniques in matrix free-environment if we know the matrix structure. This is a classical field; a (very restricted) selection of references: Curtis, Powell; Reid,1974; Coleman, Moré, 1983; Coleman, Moré, 1984; Coleman, Verma, 1998;

The procedure

- * Estimate the matrix A_i by a few matvecs
- * Get the preconditioner M_i directly from A_i
- extensions to SPD (Hessian) approximations; extensions to use both A and A^T in automatic differentiation; more sophisticated estimation of resulting entries (substitution methods)
- to get only a part of the matrix which changes in the outer iterations: partial graph coloring, Gebremedhin, Manne, Pothen, 2004.



The 2D nonlinear convection-diffusion problem (Kelley, 1995); 5-point finite diferences; uniform grid 70×70 ; first 8 systems; ILUT(0.1,5)

A-matrix	M-matrix	CG-its
A^1	M^1	25
A^2	M^1	98
A^3	M^1	90
A^4	M^1	135
A^5	M^1	179
A^6	M^1	229
A^7	M^1	275
A^8	M^1	345
A^{1-8}	M^{1-8}	25 ± 10

$$\Delta u - Ru\nabla u = 2000x(1-x)y(1-y), \ R = 500$$

Freezing the preconditioner may not be enough



What do we gain if we use a sparsified pattern for preconditioner computation?

- 1. Traditionally: Sparsified pattern \rightarrow cheaper preconditioner computation
- Proposal 1: Sparsified pattern + matrix-free environment → cheaper but approximate matrix estimation via matvecs (Cullum, T., 2004)
- 3. Proposal 2: Freezing the matrix pattern in a matrix-free environment: use of the sparsified pattern of a different matrix from a sequence.
- 4. Proposal 3: Freezing the preconditioner pattern (from a different preconditioner)



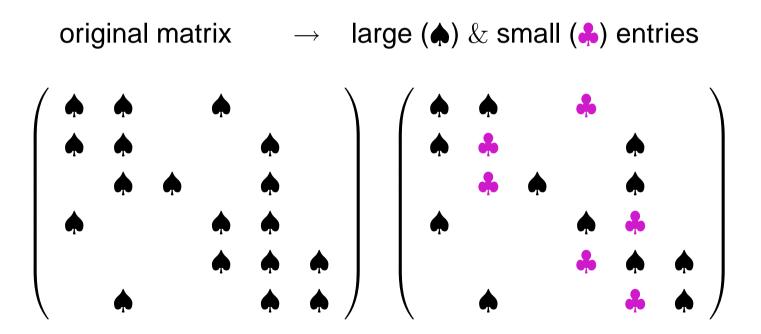
3. Reuse of matrix patterns: II.

Traditionally: Sparsified pattern leads to cheaper preconditioner computation.



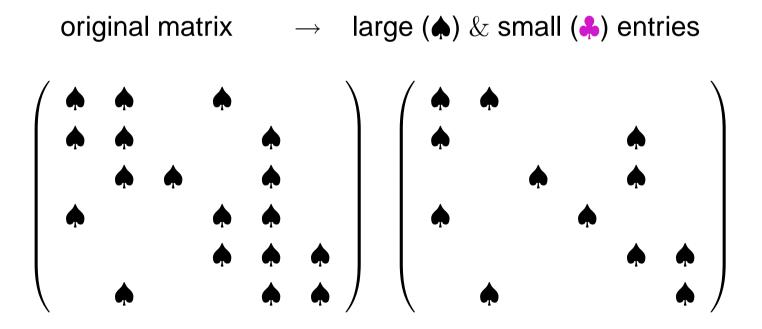
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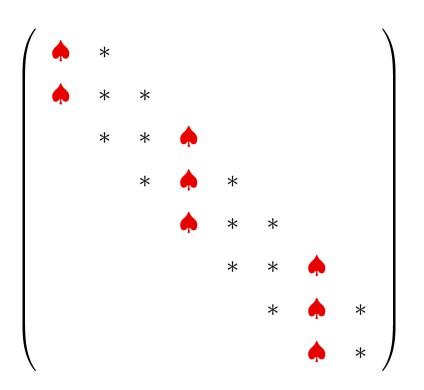
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First, a gentle introduction into matrix estimation

3. Reuse of matrix patterns: Proposal 1

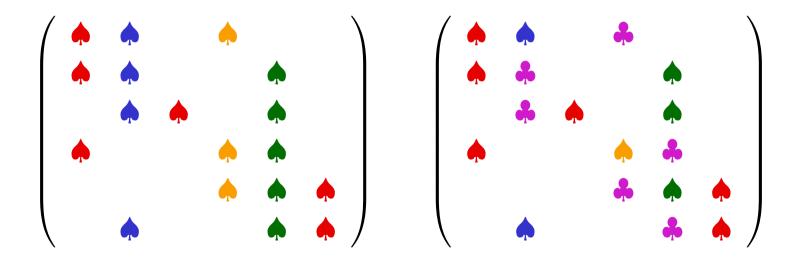


Columns with "red spades" can be computed at the same time in one matvec since sparsity patterns of their rows do not overlap.

Namely, $A(e_1 + e_4 + e_7)$ computes entries in the columns 1, 4 and 7.



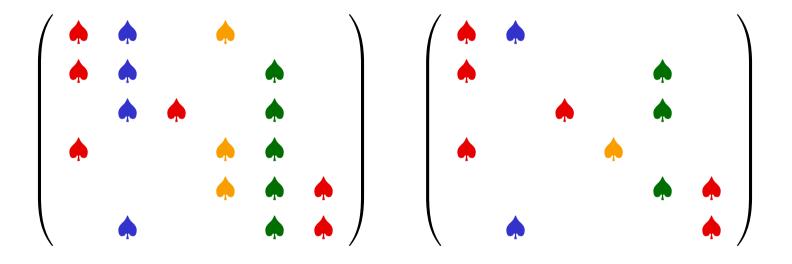
four matvecs needed \rightarrow large (coloured \spadesuit) & small (\clubsuit) entries





3. Reuse of matrix patterns: Proposal 1

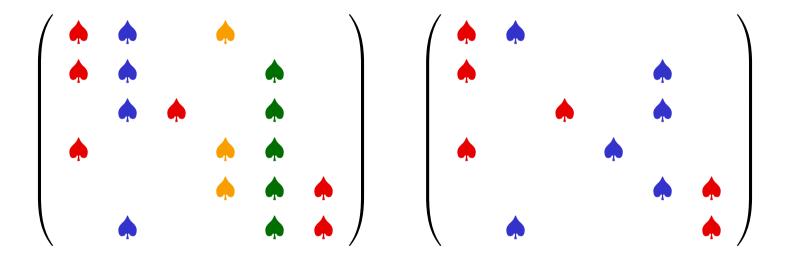
large (coloured \spadesuit) & small (\clubsuit) entries \rightarrow only two matvecs needed





3. Reuse of matrix patterns: Proposal 1

large (coloured \spadesuit) & small (\clubsuit) entries \rightarrow only two matvecs needed





Proposal 2: Freezing the matrix pattern in a matrix-free environment: use of the sparsified pattern of a different matrix from a sequence. Driven cavity flow, R = 500, ILUT($1.0 * 10^{-6}, 25$); Newton's method

No. A-matrix	No. P-matrix	CG-its
A^1	M^1 via A^1 and pattern of \widehat{A}^1	44
A^2	M^2 via A^2 and pattern of \widehat{A}^1	38
A^3	M^3 via A^3 and pattern of \widehat{A}^1	41
A^4	M^4 via A^4 and pattern of \widehat{A}^1	42
A^5	M^5 via A^5 and pattern of \widehat{A}^1	43
A^2	M^2 via A^2 and pattern of \widehat{A}^2	42
A^3	M^3 via A^3 and pattern of \widehat{A}^3	38
A^4	M^4 via A^4 and pattern of \widehat{A}^4	43
A^5	M^5 via A^5 and pattern of \widehat{A}^5	42

M Tume Number of matvecs due to the use of sparsified patterns: $51 \rightarrow 26$ 15



Proposal 3: Freezing the preconditioner pattern (for preconditioners with pattern input)

 Determination of a suitable pattern of preconditioner may be sometimes rather difficult

Our approach:

- Find a pattern for A_0 by a sophisticated / time-consuming method using both symbolic/numeric information
- Use the pattern to get preconditioners M_0, M_1, \ldots
- Restart if necessary



old SPAI versus old LS based on old SPAI pattern

The 2D nonlinear convection-diffusion problem (Kelley, 1995); 5-point finite diferences; uniform grid 70×70 ; first 8 systems; SPAI(0.0,5,5); preconditioner size = 87300

NO UPDATES		
Matrix	old_SPAI_its	$old_LS/SPAI_its$
A^1 / M^1	50	49
A^2 / M^1	76	71
A^3 / M^1	89	79
A^4 / M^1	113	134
A^5 / M^1	138	147
A^6 / M^1	157	161
A^7 / M^1	201	173
A^8 / M^1	238	179

$$\Delta u - Ru\nabla u = 2000x(1-x)y(1-y), \ R = 500$$



SPAI versus LS with old SPAI pattern

The same 2D nonlinear convection-diffusion problem (Kelley, 1995); SPAI(0.0,5,5)

new SPAI versus new LS with old SPAI pattern

Number of iterations in SPAI:	50 ± 8
Number of iterations in LS with old SPAI pattern:	50 ± 8
Time for computing SPAI preconditioner	=0.62 – 0.69 s
Time for computing LS preconditioner with old SPAI pattern	=0.22 s
Sequential time for 50 iterations	pprox 0.1 s



4. Reuse of matrix: Entrywise updates

Exploiting both pattern and numerical values

 $A_0 \to A_1 = A_0 + B$



 $A_0 \to A_1 = A_0 + B$

Case I: Simple one-entry off-diagonal updates

$$B = uv^T = \alpha e_i e_j^T$$



 $A_0 \to A_1 = A_0 + B$

Case I: Simple one-entry off-diagonal updates

$$B = uv^T = \alpha e_i e_j^T$$

$$\begin{aligned} A_1^{-1} &= (A_0 + B)^{-1} = (A_0 + xy^T)^{-1} = (LDU + xy^T)^{-1} = \\ (L(D + L^{-1}xy^TU^{-1})U)^{-1} &\approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = \end{aligned}$$

$$\frac{U^{-1}(I - \alpha D^{-1}e_i e_j^T)D^{-1}L^{-1}}{1 + \alpha e_j^T D^{-1}e_i}$$



 $A_0 \to A_1 = A_0 + B$

Case I: Simple one-entry off-diagonal updates

$$B = uv^T = \alpha e_i e_j^T$$

$$A_1^{-1} = (A_0 + B)^{-1} = (A_0 + xy^T)^{-1} = (LDU + xy^T)^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} \approx U^{-1}(I + \alpha D^{-1}e_ie_j^T)^{-1}D^{-1}L^{-1} = (L(D + L^{-1}xy^TU^{-1})U)^{-1} = (L(D +$$

$$\frac{U^{-1}(I - \alpha D^{-1}e_i e_j^T)D^{-1}L^{-1}}{1 + \alpha e_j^T D^{-1}e_i}$$

- Approximation good if there is a strong matrix diagonal it can be forced by a weighted matching applied to the matrix graph
- Inversion of a Gauss-Jordan transform
- More Gauss-Jordan transforms can be accumulated in one sweep (using pattern-based conditions) ... next slide



More Gauss-Jordan transforms

• Entries for a sweep with Gauss-Jordan transforms can be found from a weighted spanning forest T of the graph G_B of a (sparsified) difference matrix $B = A_1 - A_0$.



More Gauss-Jordan transforms

• Entries for a sweep with Gauss-Jordan transforms can be found from a weighted spanning forest T of the graph G_B of a (sparsified) difference matrix $B = A_1 - A_0$.

The procedure

- 1. Find the weighted forest T of G_B
- 2. Find the order of Gauss-Jordan transforms corresponding to the edges of T (It can be proved that it is feasible)
- 3. Add to the product of the Gauss-Jordan transforms other nonzeros entries of B (It can be shown which entries, based on simple structural conditions)



Updates of diagonal + subdiagonal representing convection changes in a 2D convection-diffusion problem, n = 10000

2D CD problems with a 1D - convection shift		
Shift	$NO_updates_its$	$CONV_updates_its$
0.1	52	54
0.2	58	60
0.3	67	60
0.4	68	61
0.5	75	65
0.6	81	73
0.7	100	76
0.8	121	78
0.9	146	81
1.0	186	82

New preconditioner: 34 iterations



Updates of diagonal + subdiagonal representing convection changes in a 2D convection-diffusion problem (different from the previous one), n = 10000

2D CD problems with a 1D - convection shift		
Shift	$NO_updates_its$	$CONV_updates_its$
0.1	34	33
0.2	36	35
0.3	39	34
0.4	38	33
0.5	44	34
0.6	56	38
0.7	53	34
0.8	63	34
0.9	69	30

New preconditioner: 35 iterations



4. Reuse of matrix: Triangular updates

Exploiting both pattern and numerical values

 $A_0 \to A_1 = A_0 + B$



 $A_0 \rightarrow A_1 = A_0 + B$ Case II: Triangular updates $B = L_B + D_B + U_B$



 $A_0 \to A_1 = A_0 + B$

Case II: Triangular updates

 $B = L_B + D_B + U_B$

$$A_1^{-1} = (A_0 + B)^{-1} = (A_0 + L_B + D_B + U_B)^{-1} = (LDU + L_B + D_B + U_B)^{-1} = (L(D + L^{-1}(L_B + D_B + U_B)U^{-1})U)^{-1} \approx U^{-1}(I + D(D_B + U_B)U^{-1})^{-1}D^{-1}L^{-1} = (DU + D_B + U_B)^{-1}L^{-1}$$



 $A_0 \to A_1 = A_0 + B$

Case II: Triangular updates

 $B = L_B + D_B + U_B$

$$A_1^{-1} = (A_0 + B)^{-1} = (A_0 + L_B + D_B + U_B)^{-1} = (LDU + L_B + D_B + U_B)^{-1} = (L(D + L^{-1}(L_B + D_B + U_B)U^{-1})U)^{-1} \approx U^{-1}(I + D(D_B + U_B)U^{-1})^{-1}D^{-1}L^{-1} = (DU + D_B + U_B)^{-1}L^{-1}$$

- Approximation good in many practical situations
- It can be shown that it behaves theoretically well if ||L I|| is small
- ... but not only in this case, as the subsequent experiments show



Triangular update versus no update

The 2D nonlinear convection-diffusion problem (Kelley, 1995); 5-point finite diferences; uniform grid 70×70 ; first 8 systems; ILUT(0.1,5)

matrix / precond	CG its / no update	CG its / triangular update
A^1 / M^1	25	25
A^2 / M^1	98	30
A^3 / M^1	90	27
A^4 / M^1	135	30
A^5 / M^1	179	35
A^6 / M^1	229	36
A^7 / M^1	275	36
A^8 / M^1	345	53
A^{1-8} / M^{1-8}	25 ± 10	25 ± 10



5. Conclusions

- Nonsymmetric preconditioners in the form of decompositions can be successfully updated by algebraic techniques.
- Shown to be efficient in solving nonlinear problems
- A lot of possibilities for improvements under investigation * e.g., combination of rank-1 and rank-n updates * e.g., sparse updates of incomplete factorizations
- Last but not least: even pattern recycling can help
- A lot of possible combinations with matrix-free environment